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Fanuc Loader Robot LR-0 & LR-1, (Control Unit: Fanuc Series 16/18), Connection Maintenance Manual, (Mechanical Unit), Language ENGLISH, Pages 202, B-61903E/02, X2 Fanuc Robot Model , Descriptions, Fujitsu Fanuc Ltd, Language ENGLISH, Pages 63, B-51612E, X1

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Zero Return parameter setting procedure for Fanuc 16/18 and 16i/18i Controls . Move the axis to where you think zero return should be. If you can't get to the position you would like, hold in "P" and "Cancel" on power up to bypass soft overtravels or you could change the soft overtravel limits to temporarily.

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